

THOR-LX / HIIr Instrumentation and Wiring

4.1 Overview of Instrumentation and Wiring

The THOR-LX / HIIr assembly is capable of carrying a total of 20 channels of data per leg. **Figure 4.1** is a plot showing the relative location of all the instrumentation for THOR-LX / HIIr. (Note: The knee shear and knee rotation instruments are not shown in this figure.) The layout of the instrumentation in the lower extremity was designed to maintain the high-degree of modularity, which was one of the main design goals. Each instrument has an individual lead wire to allow for easy removal and insertion for calibration and inspection.

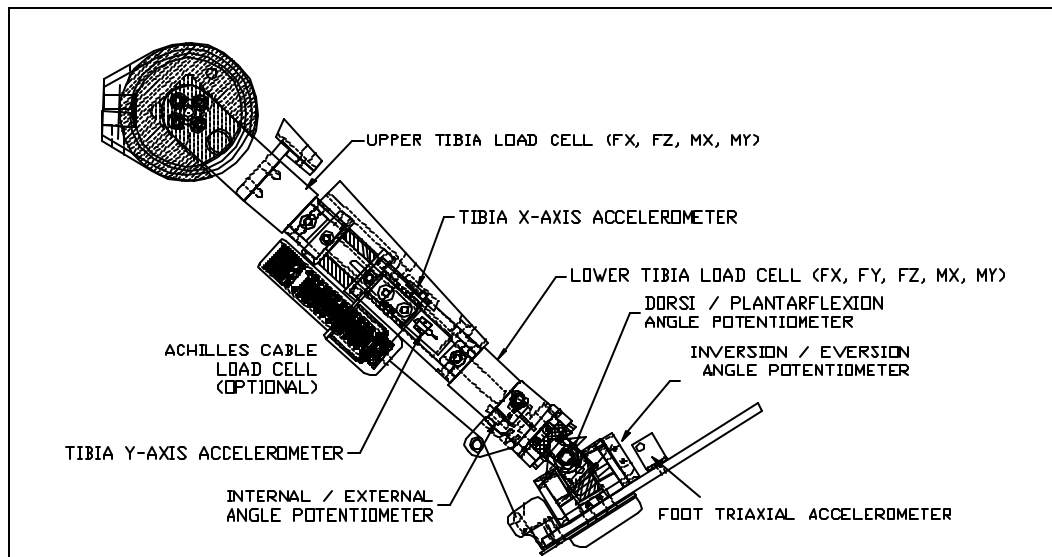


Figure #4.1 - THOR-LX / HIIr Instrumentation

4.1.1 Available Instrumentation

The THOR-LX / HIIr unit is currently capable of supporting the following instrumentation:

Knee	Knee Shear (Displacement) Knee Rotation
Lower Ex.	Upper Tibia Load Cell (4 Channels) Lower Tibia Load Cell (5 channel) Tibia Acceleration (2 ch: X, Y) Achilles Tendon Load Cell Ankle Joint Rotation Potentiometers (X, Y, Z) Foot Acceleration (X, Y, & Z)

4.1.2 Instrumentation Description

- Knee: The THOR-LX / HIIIr Knee assembly is instrumented with a miniature string potentiometer to measure the knee translation (shear) along the given axis of motion. Additionally, the rotation of the lower leg at the knee joint is measured with a potentiometer.
- C Lower Extremity: The THOR-LX / HIIIr assembly is instrumented with a pair of tibia load cells, located at the top and bottom of the tibia tube. These load cells provide the primary loading data for the lower leg structure which includes the Forces in the X, Y and Z, as well as the Moments in the X and Y. Three rotary potentiometers are used to measure the rotation of the ankle joint about the X, Y, and Z axes. A uniaxial load cell can be installed to measure the Achilles Cable tension. Finally, a pair of uniaxial and one triaxial accelerometers provide data on the acceleration of the tibia and foot assemblies.

4.1.3 Standard Instrumentation Specifications

Table 4.1 shows the typical vendor reference for the instrument.

Table 4.1

Instrument	Vendor Reference
Uniaxial Accelerometer	Entran # EGE-73BQ-2000HD Endevco # 7264-T
Triaxial Accelerometer	Entran # EGE3-73-2000 Endevco # 7267A
Rotary Potentiometer	Contelec # PD210-4B
Upper Tibia Load Cell	Denton # B-4353-D
Lower Tibia Load Cell	Denton # B-4929-D

4.2 Wire Routing and Strain Relief for THOR- LX / HIIIr Instrumentation

The wire routing and strain relief for the instrumentation in the THOR-LX / HIIIr assembly is fairly straightforward. Each instrument is first strain relieved to a mechanical component to prevent damage to the wiring during testing. Then the wires are grouped into bundles and further strain relieved at various points in the assembly. The skin was designed to provide a wire channel up each side of the tibia assembly, as described in Section 3.2.2, Step #35 describes this routing and provides a photo. Additional information is provided for each instrument below:

Upper Tibia Load Cell: The wire from this load cell exits through the hole provided at the rear of the tibia skin - just below the knee. The hole is at the top of the tibia skin zipper assembly.

Lower Tibia Load Cell: The wire from this load cell is routed up the right side of the lower leg and is bundled with the wires from the X & Z axis rotary potentiometers. These wires are strain relieved to the left side of the Achilles Spring Tube Base using a 3/16" wire clamp and a #6-32 x 1/2" BHSCS {5/64}. These wires continue up and exit through the hole provided at the rear of the tibia skin - just below the knee.

Tibia Uniaxial Accelerometers: The wires from these accelerometer units exit the right side of the tibia guard and are bundled with the wires from the foot triaxial accelerometer and the Y axis rotary potentiometers. These wires are strain relieved to the right side of the Achilles Spring Tube Base using a 3/16" wire clamp and a #6-32 x 1/2" BHSCS {5/64}. These wires continue up and exit through the hole provided at the rear of the tibia skin - just below the knee.

Foot Triaxial Accelerometer: The wire from this accelerometer unit exits the molded foot cavity to the right and is strain relieved to the front side of the Y axis rotary potentiometer housing with a 3/16" wire clamp using a #6-32 x 3/8" BHSCS {5/64}. A small amount of slack must be provided in this wire between the instrument and the strain relief to allow for dorsi / plantar flexion motion of the foot. This wire is then bundled with the wire from the Y axis rotary potentiometers. These wires are strain relieved to the right side of the Achilles Spring Tube Base using a 3/16" wire clamp and a #6-32 x 1/2" BHSCS {5/64}. These wires continue up and exit through the hole provided at the rear of the tibia skin - just below the knee.

X axis rotary potentiometer: This wire is strain relieved to the potentiometer housing with a 1/8" wire clamp using a #6-32 x 3/8" BHSCS {5/64}. This wire is strain relieved again at the front left side of the Y axis rotation joint with a 1/8" wire clamp using a #6-32 x 3/8" BHSCS {5/64}. A small amount of slack must be provided in this wire between the instrument and the strain relief to allow for dorsi / plantar flexion motion of the foot. This wire is then bundled with the wire from the lower tibia load cell. These wires are strain relieved to the left side of the Achilles Spring Tube Base using a 3/16" wire clamp and a #6-32 x 1/2" BHSCS {5/64}. These wires continue up and exit through the hole provided at the rear of the tibia skin - just below the knee.

Y axis rotary potentiometer: This wire is strain relieved to the potentiometer housing with a 1/8" wire clamp using a #6-32 x 3/8" BHSCS {5/64}. This wire then runs up the right side of the leg and is bundled with the wires from the foot triaxial accelerometer. These wires are strain relieved to the right side of the Achilles Spring Tube Base using a 3/16" wire clamp and a #6-32 x 1/2" BHSCS {5/64}. These wires continue up and exit through the hole provided at the rear of the tibia skin - just below the knee.

Z axis rotary potentiometer: This wire is strain relieved to the front of the Top Torque Base with a 1/8" wire clamp using a #6-32 x 3/8" BHSCS {5/64}. The wire is routed up the right side of the lower leg and is bundled with the wires from the X axis rotary potentiometer and the lower tibia load cell. These wires are strain relieved to the left side of the Achilles Spring Tube Base using a 3/16" wire clamp and a #6-32 x 1/2" BHSCS {5/64}. These wires continue up and exit through the hole provided at the rear of the tibia skin - just below the knee.

4.3 Wire Markers

In order to keep track of the instrumentation wiring used for the THOR-LX / HIIIr, a wire marking system has been employed. This system involves an alpha-numeric marking strip for each instrument wire and connector wire, as well as, a color coded marker to denote the instrument type. **Table 4.2** below provides a reference to the colors and their meanings.

Table 4.2

Wire Marker Color	Instrument Type
ORANGE	LOAD CELLS
RED	ACCELEROMETERS
BLUE	POTENTIOMETERS

A complete listing of the instrumentation and related wire markers is provided in **Table 4.3** for reference. Please refer to the notes at the bottom of the table for further information.

Table 4.3

THOR COMPONENT AND SENSOR	WIRE MARKER
KNEE	
Knee Rotation	K@{Blue}RP
Knee Shear Displacement	K@{Blue}SD
LOWER EXTREMITY	
Lower Tibia Load Cell (Fx, Fz, Mx, My)	LT@{Orange}**
Upper Tibia Load Cell (Fx, Fz, Mx, My)	UT@{Orange}**
Ankle Rotation	A*@{Blue}RP

Notes:

Colors in { } indicate a blank space of the corresponding color.

* Above indicates X, Y, OR Z axis

** above indicates Force X,Y,Z or Moment X,Y,Z (i.e. FX, MX)

Above indicates POT # 1, 2, OR 3

@ Above indicates L or R for Left or Right

4.4 THOR-LX / HIIIr Instrumentation Wiring

4.4.1 Commercial THOR-LX / HIIIr Sales

The THOR-LX / HIIIr units which are sold commercially are provided with the instrumentation requested in the sales agreement. The instrument wires on these units are left bare ended for the individual customers to attach the connector of their choice. This allows various customers to select the connector which will mate with the desired DAQ system. All of the load cells and accelerometers will be provided with their own individual calibration sheets which contain the necessary wiring information. For the Rotary Potentiometer Units, please refer to the wiring directions provided below.

Ankle- X Rotary Potentiometer (marked AXL{Blue}RP or AXR{Blue}RP)

Ankle- Y Rotary Potentiometer (marked AYL{Blue}RP or AYR{Blue}RP)

Ankle- Z Rotary Potentiometer (marked AZL{Blue}RP or AZR{Blue}RP)

<u>Function</u>	<u>Wire Color</u>
+ Excitation	Red
- Excitation	Black
+ Signal	Green
- Signal	White

4.4.2 Leased THOR-LX / HIIIr Units

Initially, the method for adapting the THOR-LX / HIIIr instrument connectors to other laboratory data acquisition systems had been an point of concern. This problem has been solved with the use of THOR-LX / HIIIr Connector Wires. The instrumentation from the lower extremity is connected to the laboratory data acquisition system through the use of the Connector Wires. These Connector Wires feature a mating LEMO connector on one end to fit the THOR-LX / HIIIr unit's LEMO connectors and a blank wire at the other end. The blank end of the connector wire can be soldered to the appropriate connector necessary for mating with the testing laboratory data acquisition system. Each connector wire is individually marked to mate with a specific instrument on the lower extremity. **Table 4.4** describes the correct wire color assignments for the connector wires. This table should provide all of the necessary information to correctly wire the appropriate mating connectors for the laboratory data acquisition system.

TABLE 4.4

Ankle- X Rotary Potentiometer (marked AXL{Blue}RP or AXR{Blue}RP)

Ankle- Y Rotary Potentiometer (marked AYL{Blue}RP or AYR{Blue}RP)

Ankle- Z Rotary Potentiometer (marked AZL{Blue}RP or AZR{Blue}RP)

<u>Function</u>	<u>Wire Color</u>
+ Excitation	Red
- Excitation	Black
+ Signal	Green
- Signal	White

Upper Tibia Load Cell (marked UTL{Orange}**and UTR{Orange}**)

where * indicates Fx, Fz, Mx, or My

Lower Tibia Load Cell (marked LTL{Orange}**and LTR{Orange}**)

where * indicates Fx, Fz, Mx, or My

Forces:

<u>Axis:</u>	<u>Function:</u>	<u>Wire Color:</u>
X, Y*, Z	+ Excitation	Red
	- Excitation	Black
	+ Signal	Green
	- Signal	White

Moments:

<u>Axis:</u>	<u>Function:</u>	<u>Wire Color:</u>
X, Y	+ Excitation	Red
	- Excitation	Black
	+ Signal	Green
	- Signal	White

* Lower Tibia Load cell includes Fy capability.

4.5 Instrumentation Excitation and Ground Requirements

For all of the instrumentation on the THOR-LX / HIIIr, the excitation voltage and ground requirements are supplied below. The instrumentation for this unit was all designed to have the same excitation requirements - thus simplifying the power requirements. The current requirements are minimal, i.e. 100 mA per instrument is more than sufficient.

All + Excitation Terminals must be connected to a 10.00 (+/- 0.05) V DC power supply.
 All - Excitation Terminals must be connected to a ground (i.e. 0.0 V DC) source.
 All Ground Terminals must be connected to a ground (i.e. 0.0 V DC) source.

4.6 Data Acquisition

The proper connection of the THOR-LX / HIIIr instrumentation to the laboratory data acquisition system is essential to the correct measurement of the various forces, moments, accelerations and deflections. **Table 4.5** provides a reference to the proper data acquisition requirements for each channel. These requirements include the channel configuration and range requirements for each of the instruments.

The data acquisition channel configuration defines how to measure the voltage difference for the output of each channel. For all of the instruments of the THOR-LX / HIIIr unit, the channel configuration is either differential or referenced single-ended. The term DIFF denotes a differential configuration in which the + Signal lead is connected to a HI Input Channel and the - Signal lead is connected to a LO Input Channel. The data acquisition system is then configured as a differential input to measure the voltage difference between the HI and LO channel inputs.

WARNING: DO NOT CONNECT THE - SIGNAL LEAD TO GROUND OR THE INSTRUMENTATION MAY BE PERMANENTLY DAMAGED.

For typical data acquisition systems, differential input configurations require two channels of the data acquisition system for each instrument channel (i.e. a HI and LO channel for each axis of a load cell, etc.). All of the load cells and accelerometers used in the THOR-LX / HIIIr instrumentation require a differential configuration for the proper data acquisition.

The term RSE denotes a Referenced Single-Ended configuration in which the + Signal lead is connected to a HI input channel. The data acquisition system is then configured as a referenced single-ended input to measure the voltage difference between the HI channel input and the ground reference.

In addition to the channel configuration, the other critical information needed to setup the data acquisition for the THOR-LX / HIIIr is the expected output voltage range for each of the instruments. This output voltage range is used to adjust the individual channel sensitivity of the data acquisition system to obtain the highest possible data resolution. The use of the output voltage ranges listed in the table will insure that none of the data is clipped for extreme loading that may occur.

Table 4.5

THOR COMPONENT AND SENSOR	DAQ Configuration	Output Voltage Range
LOWER EXTREMITY		
Lower Tibia Load Cell (Fx, Fy, Fz, Mx, My)	DIFF (5 CH)	-30 to 30 mV
Upper Tibia Load Cell (Fx, Fz, Mx, My)	DIFF (4 CH)	-30 to 30 mV
Ankle Rotation	RSE	0 to 10 V

4.7 THOR-LX / HIIIr Instrumentation - Polarity

Table 4.6

INSTRUMENT LOCATION	SAE Dummy Manipulations for Load Cell Polarity	THOR-LX Polarity
Knee Rotation	Extension	N/A
Knee Shear Displacement (Left)	Hold Femur in Place, Tibia Forward	+
Upper Tibia (Left: Force X-axis)	Tibia Forward, Knee Rearward	+
Upper Tibia (Left: Force Z-axis)	Tibia Downward, Femur Upward	+
Upper Tibia (Left: Moment X-axis)	Ankle Leftward, Hold Knee in Place	+
Upper Tibia (Left: Moment Y-axis)	Ankle Forward, Hold Knee in Place	+
Lower Tibia (Left: Force X-axis)	Ankle Forward, Knee Rearward	+
Lower Tibia (Left: Force Y-axis)	Ankle Rightward, Knee Leftward	+
Lower Tibia (Left: Force Z-axis)	Ankle Downward, Knee Upward	+
Lower Tibia (Left: Moment X-axis)	Ankle Leftward, Hold Knee in Place	+
Lower Tibia (Left: Moment Y-axis)	Ankle Forward, Hold Knee in Place	+
Tibia Acceleration (X axis)	Tibia Forward	+
Tibia Acceleration (Y axis)	Tibia Right	+
Achilles Tendon Load Cell - Right	Tension in Cable	-
Ankle Left X-axis Rotation	Inversion	+
	Eversion	-
Ankle Left Y-axis Rotation	Dorsiflexion	+
	Plantarflexion	-
Ankle Left Z-axis Rotation	Internal Rotation	-
	External Rotation	+
Foot Acceleration (X axis)	Foot Forward	+(1) +(2)
Foot Acceleration (Y axis)	Foot Rightward	-(1) +(2)
Foot Acceleration (Z axis)	Foot Down	-(1) +(2)
Knee Rotation	Extension	N/A
Knee Shear Displacement (Right)	Hold Femur in Place, Tibia Forward	+
Upper Tibia (Right: Force X-axis)	Tibia Forward, Knee Rearward	+
Upper Tibia (Right: Force Z-axis)	Tibia Downward, Femur Upward	+
Upper Tibia (Right: Moment X-axis)	Ankle Leftward, Hold Knee in Place	+
Upper Tibia (Right: Moment Y-axis)	Ankle Forward, Hold Knee in Place	+
Lower Tibia (Right: Force X-axis)	Ankle Forward, Knee Rearward	+
Lower Tibia (Right: Force Y-axis)	Ankle Rightward, Knee Leftward	+
Lower Tibia (Right: Force Z-axis)	Ankle Downward, Knee Upward	+
Lower Tibia (Right: Moment X-axis)	Ankle Leftward, Hold Knee in Place	+

Lower Tibia (Right: Moment Y-axis)	Ankle Forward, Hold Knee in Place	+
Tibia Acceleration (X axis)	Tibia Forward	+
Tibia Acceleration (Y axis)	Tibia Right	+
Achilles Tendon Load Cell - Right	Tension in Cable	-
Ankle Right X-axis Rotation	Inversion	- (*)
	Eversion	+ (*)
Ankle Right Y-axis Rotation	Dorsiflexion	+
	Plantarflexion	-
Ankle Right Z-axis Rotation	Internal Rotation	+ (*)
	External Rotation	- (*)
Foot Acceleration (X axis)	Foot Forward	+ (1) +(2)
Foot Acceleration (Y axis)	Foot Rightward	- (1) +(2)
Foot Acceleration (Z axis)	Foot Down	- (1) +(2)

* Indicates potentiometers which have a polarity that is opposite the SAE J211 system.

(1) Indicates the polarity for a single triaxial unit which is mounted as specified in the THOR-LX drawing package and user's manual.

(2) Indicates the polarity for a tri-pack block which is mounted as specified in the THOR-LX drawing package and user's manual.